GP

Genetic Programing

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GP Overview

• What is Genetic Programing (GP)?

- Methodology
 - Creating Individuals and Populations
 - Testing Fitness
 - Selection and Genetic Operations
 - Control Parameters
- Issues with GP
- Summary

What is GP?

• Automatic Programing

• Give a computer a problem and solve it on its own.

• Evolutionary algorithm

• Uses Darwin's Theory of Evolution

- Those with the greatest ability (or fitness) to survive pass their genetic material to the next generation
- Survival of the fittest

GP Methodology

- 1. Start with a Problem
- 2. Create Individuals for a Population• Composed of genes (represent code)
- 3. Test Each Individual's Abilityo Fitness Test (dependent on problem)
- 4. Select Individuals to Reproduce New Generation
- 5. Genetic Operations (for variation)
- 6. Multiple Generations for evolution

• Final generation has ideally evolved into a exceptional solution

Problem: Robot Soccer

- Evolve a robot soccer team into World Cup Champions
- Need to be able to follow the ball
- Use GP to evolve programming code for good ball following.



Creating Individuals

• Made up of genes (i.e. code)

- Genes:
 - 1. Functions—provide argument for a function
 - Nodes with branches
 - 2. Terminals—numerical input
 - Nodes without branches
- Depth—number of levels of nodes

Terminals

"Genetic" Code $\rightarrow (2.2 - (\frac{X}{11})) + (7 \times \cos(Y))$

(2.2)

Individual with

depth of four

+

7

Functions

(cos

Creating a Population

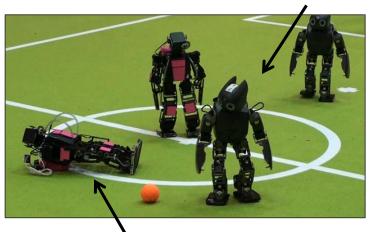
- For evolution to occur need a large population
- Need a variation of individuals
 - Several techniques in GP
 - Grow—create individuals with max., m, depth
 - 2. Full—create individuals with final, *d*, depth
 - 3. Ramped Half-and-Half—both Grow and Full, md

Test Individuals' Ability

• Fitness test

- Dependent on the problem
- Example robot soccer:
 - Robot's ability to follow the ball

High Fitness



Low Fitness

Select Individuals to Reproduce

• Need to transfer individual's code to the next generation

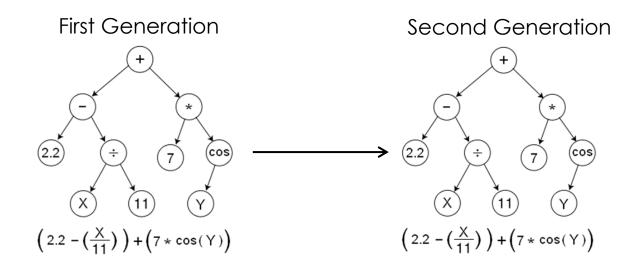
Want a new and better generation of robots
 Different methods fitness of selection
 Overall picked based on fitness

• Ways to change up and transfer individual's code to the next generation

- 1. Reproduction
- 2. Crossover
- 3. Mutation
- 4. Others: editing, permutation, encapsulation, and decimation.

Important to have variation to allow for evolution!

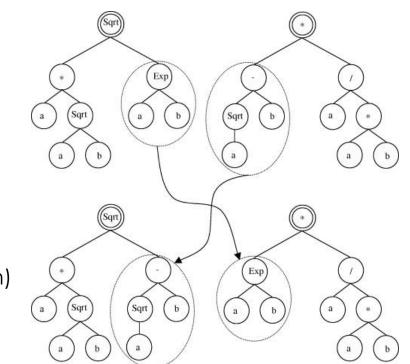
• Reproduction—Individuals selected are sent to next generation



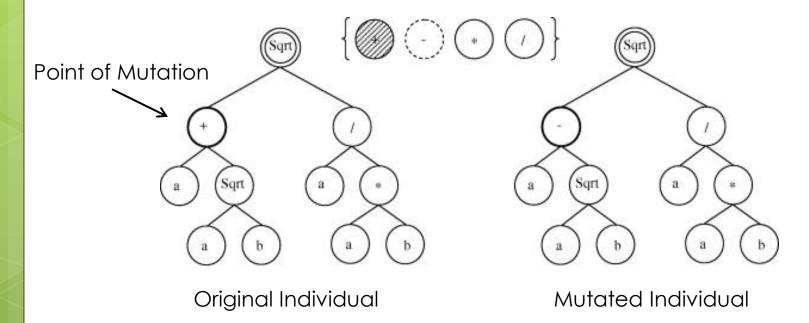
• Crossover—two individuals swap pieces of code and make two new individuals.

Parent Generation

New Generation (Children)



Mutation—random point in code is deleted and replaced making new code



Generations

- Repeat genetic operations of fit individuals over time.
 - Overall fitness of population increases over time.

 Ideally, last generation will give us World Cup Champions!



Control Parameters

- Population size
- Maximum number of generations
- Probability of genetic operations
- Probability of selection and reproduction
- Not too constrictive—can't evolve!
- Not too laissez-faire—can evolve too fast or not enough for quality evolution to occur!

Issues with GP

• Massive computer power needed.

• Mostly in computing fitness

- "Genetic" code is vital for solving the problem.
- Can be persnickety with control parameters.
- Long run times.

Summary

- GP uses methods from evolution to solve problems
- Evolve populations of individuals comprised of code
- Goal is over generations a fit population or excellent solution will evolve

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Thank you! Questions?